

Review of previous lecture (June 27)

Rh analysis of 1d Ising model

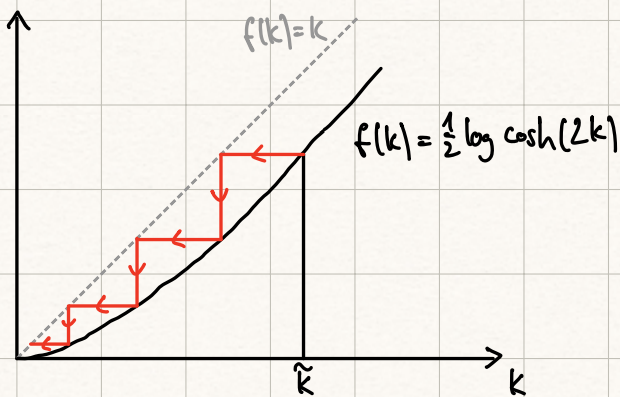


Rh-transformed
Hamiltonian:

$$-\beta H' = k_0' \mathbb{1} + k_1' \sum_{\langle ij \rangle} \sigma_i \sigma_j$$

only nearest-neighbor interaction!

\Rightarrow Rh equations exactly solvable

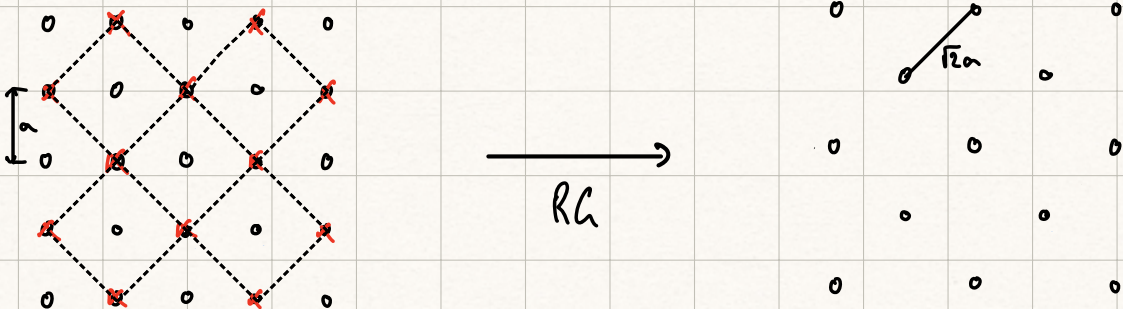


two fixed points:

$$k_n^* = \frac{1}{2} \log \cosh(2k_n^*)$$

- 1.) $k_n^* = 0$ ($T \rightarrow \infty$): Complete disorder
- 2.) $k_n^* = \infty$ ($T = 0$): perfect order

Rh analysis of 2d Ising model



RG-transformed Hamiltonian:

$$-\beta H' = K_0' L + \underbrace{\frac{1}{2} K_1' (\sigma_1 \sigma_2 + \dots + \sigma_3 \sigma_4)}_{\text{nearest-neighbor interaction}} + \underbrace{K_2' (\sigma_1 \sigma_3 + \sigma_2 \sigma_4)}_{\text{next-to-nearest neighbor int.}} + \underbrace{K_3' \sigma_1 \sigma_2 \sigma_3 \sigma_4}_{\text{4-spin interaction}}$$

additional RG transformations will generate even more couplings!

\Rightarrow RG equations NOT exactly solvable!

RG transformed correlation length:

$$\xi_2(\beta) = \frac{\xi}{\ell} \quad \text{when block spins with spacing } \ell \cdot a \text{ are generated}$$

general properties of RG transformations

consider the general form of a RG transformation

$$[k'] = R_l[k] \quad l > 1$$

where $[k]$ and $[k']$ is the set of coupling constants before and after the RG transformation

- the RG transformation is in general a complicated non-linear transformation (see 2d Ising model)
- in general the set $[k']$ is larger than $[k]$
- RG transformations form a semi-group, i.e. products of RG transf. are also RG transformations.

$$[k'] = R_{e_1}[k]$$

$$[k''] = R_{e_2}[k'] = R_{e_2} \cdot R_{e_1}[k] = R_{e_1 \cdot e_2}[k]$$

$$\text{and } R_{e=1}[k] = k$$

however, generally the inverse R_l^{-1} does not exist ("semi-group")

- in general any RG transformation can be defined via a projection operator in the partition function:

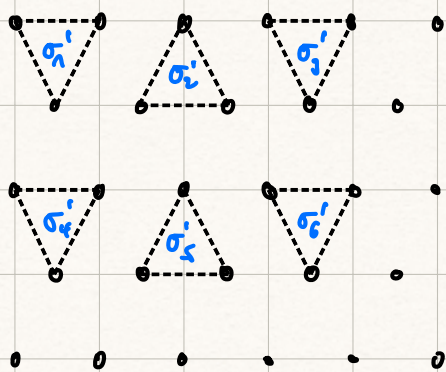
$$e^{-\beta H([k'], \sigma'_I)} = \text{Tr}'_{\{\sigma_I\}} e^{-\beta H([k], \sigma_I)}$$

block spins \leftarrow restricted trace \leftarrow

$$\equiv \text{Tr}_{\{\sigma_I\}} P(\sigma_I, \sigma'_I) e^{-\beta H([k], \sigma_I)}$$

\hookrightarrow projection operator, constructed such that block spins σ'_I have same range of values like σ_I

example: 2d Ising model on a triangular lattice



block spins

$$\sigma'_I = \text{sign} \left(\sum_{i \in I} \sigma_i \right) = \pm 1$$

$$\Rightarrow P(\sigma_i, \sigma'_I) = \prod_I \delta(\sigma'_I - \text{sign}(\sum_{i \in I} \sigma_i))$$

in general the projection operator must satisfy the following conditions:

a) $P(\sigma_i, \sigma'_I) \geq 0 \Rightarrow$ guarantees $e^{-\beta H([\mathbf{k}'], \sigma'_I)} \geq 0$

b) $P(\sigma_i, \sigma'_I)$ reflects symmetries of system
 \Rightarrow guarantees that $H([\mathbf{k}'])$ and $H([\mathbf{k}])$ have the same form, only couplings are changing

c) $\sum_{\{\sigma'_I\}} P(\sigma_i, \sigma'_I) = 1$

\Rightarrow guarantees invariance of partition functions

$$Z_{N'}[\mathbf{k}'] = \text{Tr}_{\{\sigma'_I\}} e^{-\beta H([\mathbf{k}'], \sigma'_I)}$$

$$= \text{Tr}_{\{\sigma'_I\}} \text{Tr}_{\{\sigma_i\}} P(\sigma_i, \sigma'_I) e^{-\beta H([\mathbf{k}], \sigma_i)}$$

$$= \text{Tr}_{\{\sigma_i\}} e^{-\beta H([\mathbf{k}], \sigma_i)} = Z_N[\mathbf{k}]$$

in practice condition c) is not fulfilled as the set of couplings $[\mathbf{k}']$ needs to be truncated

the power of the RG is based on the fact that it is much easier and systematic to approximate $[k']$ than the partition function Z

fixed points

at each RG step only a finite number of degrees of freedom are being coarse grained

\Rightarrow RG transformations have to be analytic

for calculation of partition function in the thermodynamic limit $N \rightarrow \infty$ an infinite number of RG steps is required

\Rightarrow free energy can become non-analytic \rightarrow phase transitions

consider a series of n RG transformations:

- coarse graining length is l^n and system is described by a set of couplings $k_0^{(n)}, k_1^{(n)}, \dots$
- at each stage (for each n) the system can be characterized by a point in the space labeled by the axes k_0, k_1, k_2, \dots
- RG transformations trace out a trajectory in coupling constant space
- set of all trajectories, generated by different initial sets of coupling constants define the
RG flow

- for $n \rightarrow \infty$ it is found that trajectories become attracted to fixed points with $[k^*] = R_e[k^*]$
- set of all initial conditions $[k_0]$ whose trajectories flow to a given fixed point is called the **basin of attraction** of that fixed point
- in general we know that $S[k] = \frac{S[k]}{e}$
at a fixed point we have $S[k^*] = \frac{S[k^*]}{e}$

$$\Rightarrow S[k^*] = 0 \quad \text{or} \quad S[k^*] = \infty$$

↓
trivial
fixed point

↓
critical
fixed point

- using $S[k] = e S[k'] = e^2 S[k''] = e^n S[k^{(n)}]$

\Rightarrow all points in the basin of attraction of a critical fixed point have infinite scattering length!
(also called **critical manifold**)

Study RH flow near a fixed point in more detail:

$$k_n = k_n^* + \delta k_n$$

\hookrightarrow small

$$\begin{aligned} \Rightarrow k_n' &= \text{Re}[k_n] = k_n^* + \delta k_n' \\ &= k_n^* + \sum_m \underbrace{\frac{\partial k_n'}{\partial k_m}}_{\substack{= M_{nm}^L \\ \text{linearized RH} \\ \text{transformation}}} \Big|_{k_m = k_m^*} \cdot \delta k_m + o(\delta k^2) \end{aligned}$$

for the following we assume M_{nm}^L to be real, symmetric and diagonalizable

consider eigenvectors and eigenvalues of M_{nm}^L :

$$\sum_m M_{nm}^L e_m^{(i)} = \lambda_e^{(i)} e_n^{(i)}$$

$$\text{since } Re_1 \cdot Re_2 = Re_{1,2} : M^{e_1} \cdot M^{e_2} = M^{e_1, e_2}$$

$$\Rightarrow \lambda_{e_1}^{(i)} \cdot \lambda_{e_2}^{(i)} = \lambda_{e_1, e_2}^{(i)}$$

$$\Rightarrow \lambda_e^{(i)} = e^{\gamma_i} \quad (\gamma_i: \text{unknown, but independent of } e)$$

expand $\vec{\delta k}$ in terms of the eigenvectors $\vec{e}^{(i)}$:

$$\delta k_n = \sum_i a^{(i)} e_m^{(i)} \Rightarrow a^{(i)} = \sum_m e_m^{(i)} \delta k_m$$

\downarrow
scaling variables

for the sake of simplicity we will assume for the following discussion that the eigenvectors $\vec{e}^{(i)}$ are orthonormal, that is generally not true (see 2d Ising model), but does not change the main arguments

$$\begin{aligned} \Rightarrow \delta k'_n &= \sum_m \Lambda_{nm}^l \delta k_m \\ &= \sum_m \Lambda_{nm}^l \sum_i a^{(i)} e_m^{(i)} \\ &= \sum_i a^{(i)} \lambda_e^{(i)} e_n^{(i)} = \sum_i a^{(i)} e_n^{(i)} \end{aligned}$$

↓
projection of $\delta \vec{k}'$
on eigenvectors $\vec{e}^{(i)}$

depending on $\lambda_e^{(i)}$, some components of δk grow under Λ^l while others shrink:

a) $|\lambda_e^{(i)}| > 1$, i.e. $\gamma_i > 0$: $a^{(i)}$ grows during RG flow

→ relevant eigenvectors / eigenvalues / directions

b) $|\lambda_e^{(i)}| < 1$, i.e. $\gamma_i < 0$: $a^{(i)}$ shrinks during RG flow

→ irrelevant eigenvectors

c) $|\lambda_e^{(i)}| = 1$, i.e. $\gamma_i = 0$: $a^{(i)}$ invariant

→ marginal eigenvectors

⇒ for \vec{k} near \vec{k}^* (not on the critical manifold), the RG flows away from \vec{k}^* are associated with relevant eigenvectors, irrelevant eigenvectors correspond to directions of flow into the fixed point

⇒ eigenvectors corresponding to irrelevant eigenvalues span critical manifold

global and local properties of the RG flow

global behaviour of RG flow determines phase diagram:

- start at a given point $\vec{k}^{(0)} = (k_0^{(0)}, k_1^{(0)}, k_2^{(0)}, \dots)$
- iterate RG transformations: $\vec{k}^{(0)} \rightarrow \vec{k}^{(1)} \rightarrow \vec{k}^{(2)} \rightarrow \dots \rightarrow \vec{k}^{(n)}$
- identify fix points to which the system flows,
state of system described by this fixed point corresponds to the phase at the original point \vec{k}_0 . (note that partition function is preserved along RG trajectory if RG transformations are performed exactly)

classification of fixed points:

- sinks**: all trajectories flow into fix point (no relevant directions), sinks correspond to bulk phases

example: Ising model in 2d

sink at $B = \pm\infty, T = 0$: at finite B there is a finite magnetization for all T

- discontinuity / continuity** fixed points (1 relevant direction)



phase boundary

for Ising model:

all points on line $B=0$ for $T \leq T_c$

→ flow to $B=0, T=0$

first order phase transition

when crossing $B=0$ from $B>0$ or $B<0$



phase of system

no transition in vicinity

all points on line $B=0, T > T_c$

→ flow to $B=0, T=\infty$

both fixed points unstable with respect to $B=0 \rightarrow B=0^\pm$
(relevant direction)

↓
flows to sinks (a)

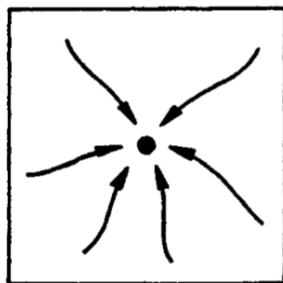
c) critical points, multi-phase coexistence (2 relevant directions)
2 couplings must be tuned to place system at the
critical point ($B=0, T=T_c$)

↓
flow into critical fixed point

Table 9.1 CLASSIFICATION OF FIXED POINTS

Codimension	Value of ξ	Type of Fixed Point	Physical Domain
0	0	Sink	Bulk phase
1	0	Discontinuity FP	Plane of coexistence
1	0	Continuity FP	Bulk phase
2	0	Triple point	Triple Point
2	∞	Critical FP	Critical manifold
Greater than 2	∞	Multicritical point	Multicritical point
Greater than 2	0	Multiple coexistence FP	Multiple coexistence

Goldenfeld p. 247



(a)



(b)

Figure 9.2 Renormalisation group flows near a critical fixed point: (a) View of flows on the critical manifold. (b) View of flows off the critical manifold.

Goldenfeld p. 248

$$\mathcal{H} = K_1 \sum_{\langle ij \rangle} S_i S_j + K_2 \sum_{ij=n.n.n.} S_i S_j \quad K_1 = J_1/k_B T \quad K_2 = J_2/k_B T$$

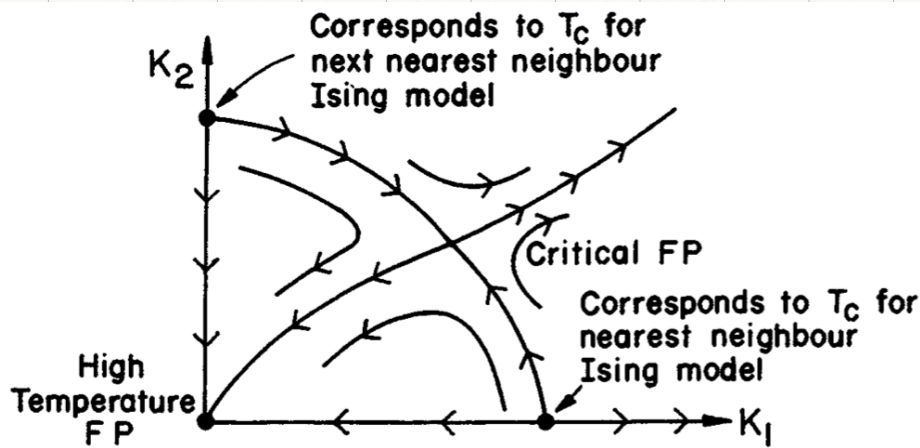


Figure 9.3 Flow diagram for an Ising model with nearest and next nearest neighbour interactions.

Goldenfeld p. 249

local properties of RG flow around critical fixed point determines critical behaviour

- trajectories on the critical manifold remain on the manifold and flow to critical fixed point
- trajectories that start slightly off the critical manifold initially flow towards critical fixed point, but are ultimately repelled due to relevant couplings
- the same relevant eigenvalues (see below) drive all slightly off-oriented systems away from critical manifold (for a given universality class), independent of original values of coupling constants
↳ universality