

### III Mean field theory

only very few interacting systems in statistical physics can be solved exactly

even just extending the very simple exact solution for the nearest-neighbour Ising model in 1d to 2d is a highly nontrivial task

↳ Lars Onsager, Phys. Rev. 65, 117

(one of the most famous papers in theoretical physics)

⇒ need methods that allow to solve general interacting systems in an approximate way.

two main options:

- 1.) mean-field theory: replace interaction with other particles by an averaged interaction ("mean field")
- 2.) Renormalization Group: more systematic framework that allows to treat interaction effects beyond the mean-field level (more later)

## mean field theory for the nearest-neighbor Ising model (1d)

$$H = -B \sum_i \sigma_i - J \sum_{\langle i,j \rangle} \sigma_i \sigma_j$$

consider  $J=0$ :

here we have  $H = -B \sum_i \sigma_i \Rightarrow$  an effective one-body problem

$\Rightarrow$  partition function factorizes into product of single-particle partition functions

$$\begin{aligned} Z_c(J=0, B, T) &= \prod_{i=1}^N (e^{\beta B} + e^{-\beta B}) \\ &= [2 \cosh(\beta B)]^N \end{aligned}$$

$$\Rightarrow m = -\frac{1}{N} \frac{\partial F}{\partial B} = \tanh(\beta B)$$

basic idea of mean-field theory:

transform  $H$  for  $J \neq 0$  to a form  $H = -\sum_i B_{\text{eff}}^i \sigma_i$



site-dependent effective field due to magnetic moment of all other spins

self-consistent problem:

- $B_{\text{eff}}$  generated by magnetic moment of all other spins:  $B_{\text{eff}} \sim m$
- however  $m$  is unknown a priori
- all spins feel external field plus mean field

$$B_{\text{eff}}^i = B_i + \sum_j^{\prime} J_{ij} \sigma_j$$

↳ couples only nearest neighbors,  
restricts sum to 2 terms

$$= B_i + \underbrace{\sum_j^{\prime} J_{ij} \langle \sigma_j \rangle}_{\text{mean field contribution}} + \underbrace{\sum_j^{\prime} (\sigma_j - \langle \sigma_j \rangle)}_{\text{fluctuations (neglected in mean field theory)}}$$

↓

external  
field

mean field  
contribution

fluctuations  
(neglected in mean field theory)

$$= B + 2Jm$$

$$\begin{array}{l} \uparrow \\ B_i = B \\ J_{ij} = J \end{array}$$

$$\Rightarrow \text{from free Ising model: } m = \tanh(\beta(B + 2Jm))$$

↓

implicit solution for  $m$   
(self consistency)

study spontaneous magnetization ( $B=0$ ):  $m = \tanh(2\beta J m)$

for solutions  $m \neq 0$  we need

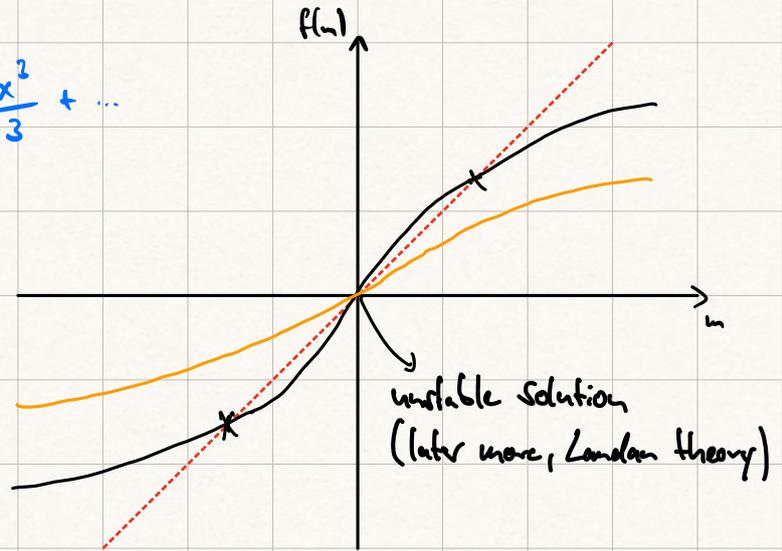
$$\tanh(2\beta J m) > m$$

for small  $m$ :  $\tanh x \sim x - \frac{x^3}{3} + \dots$

$$\Rightarrow m = \frac{2J m}{k_B \cdot T_c}$$

$$T_c = \frac{2J}{k_B}$$

↑  
phase transition  
(in contrast to exact solution!)



determine critical exponents:

$$m \sim |T - T_c|^\beta$$
$$B \sim m^\delta \quad (\text{at } T = T_c)$$
$$\chi_T = \left. \frac{\partial m}{\partial B} \right|_T \sim |T - T_c|^{-\gamma}$$

expand equation of state around  $T = T_c$ :

$$m = \tanh(\beta(B + 2Jm))$$
$$= \tanh\left(\frac{B}{k_B T} + m \cdot \tau\right) \quad \text{with } \tau = \frac{T_c}{T} = \frac{2J}{k_B T}$$

$$\sim \left(\frac{B}{k_B T} + m \tau\right) - \frac{1}{3} \left(\frac{B}{k_B T} + m \tau\right)^3 + \dots$$

↑  
small  $B$  and  $m$

for  $B=0$  we obtain:  $m(1-\epsilon) = -\frac{1}{3}m^3\epsilon^3$

$\Rightarrow m^2 = -\frac{3(1-\epsilon)}{\epsilon^3} \sim (T-T_c) \Rightarrow \underline{\beta = \frac{1}{2}}$

for  $\delta$ :  $m(1-\epsilon) = \frac{B}{k_B T} - \frac{1}{3} \left( \frac{B}{k_B T} + m\epsilon \right)^3$

$\downarrow$   
0

$= \frac{B}{k_B T} - \frac{1}{3}m^3\epsilon^3 - \frac{1}{3} \frac{B^3}{(k_B T)^3} - \frac{B}{k_B T} m^2 \epsilon^2$

$\Rightarrow \frac{B}{k_B T} \sim m^3 \Rightarrow \underline{\delta=3}$

higher order terms in powers of  $B$

justify a posteriori

for  $\gamma$ :  $\left. \frac{\partial m}{\partial B} \right|_T = \chi_T = \frac{1}{k_B T} + \chi_T \cdot \epsilon + m^2$

$\Rightarrow \chi_T(1-\epsilon) = \frac{1}{k_B T} \Rightarrow \chi_T \sim \frac{1}{T-T_c}, \underline{\gamma=1}$

liquid-gas transition, van-der-Waals equation of state

no phase transition for a free non-interacting gas

basic idea: modify ideal gas equation of state,

$$p \cdot V = N \cdot k_B \cdot T$$

so that a finite volume and an averaged interaction is taken into account