

## Review of previous lecture (May 30)

### Basic idea of Landau theory:

Postulate a Landau free energy  $L(\{k_i\})$  and an order parameter  $\eta$ . The ground state is given by the global minimum of  $L$ :  $\left. \frac{\partial L}{\partial \eta} \right|_{\eta=\eta^*} = 0$ .

constraints on  $L$ :

- symmetries of system

- for  $T \rightarrow T_c$  we have  $\eta \rightarrow 0$ ,  $L$  is analytic

$$\mathcal{L} = \frac{L}{V} = \sum_{n=0}^{\infty} a_n(\{k_i\}) \eta^n \quad (\text{uniform system})$$

$$L = \int d^3x \mathcal{L}[\eta(\vec{x})] \quad (\text{non-uniform systems})$$

-  $\eta^* = 0$  for  $T > T_c$ ,  $\eta^* \neq 0$  for  $T < T_c$

- coefficients  $a_n$  cannot be determined within Landau theory

for Ising model we obtained using only general arguments:

$$\mathcal{L} = a_2 t \eta^2 + a_4 \eta^4 - B \eta \quad \text{with } t = \frac{T - T_c}{T}$$

$\Rightarrow$  reproduces form of Ising model EOS based on explicit calculations using the Hamiltonian

## First-order phase transitions

consider now a more general form for  $\mathcal{L}$ :

$$\mathcal{L} = a_2^1 \eta^2 + a_4^0 \eta^4 + a_3^0 \eta^3 - B\eta$$

↑  
new

↑  
consider  $B=0$  in  
the following

note: linear term in  $\eta$  associated with parameter  $a_1$   
not allowed since  $\eta=0$  for  $T > T_c$

$$\frac{\partial \mathcal{L}}{\partial \eta} = 0 \Rightarrow \eta = 0 \quad \text{or} \quad \eta = -c \pm \sqrt{c^2 - \frac{a_2^1 t}{2a_4^0}}$$

real solution for

$$c^2 > \frac{a_2^1 t}{2a_4^0} \Leftrightarrow t < \frac{2a_4^0 c^2}{a_2^1} \equiv t^*$$

$$\left[ c = \frac{3a_3^0}{8a_4^0} \right]$$

- lowering  $t$  below  $t^*$  leads to 2nd minimum in  $\mathcal{L}$
- lowering  $t$  below  $t_n$  leads to a new global minimum  
(see figures)

$\Rightarrow$  value for  $\eta$  jumps discontinuously from  $\eta=0$  to  $\eta(t_n)$

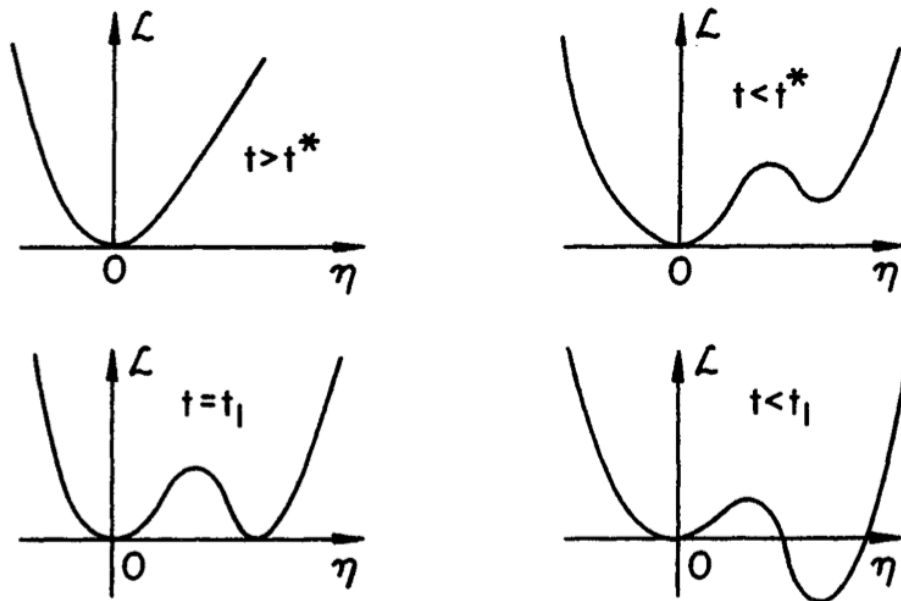


Figure 5.2  $\mathcal{L}$  as a function of  $\eta$  for various temperatures, showing the Landau theory description of a first order transition.

Goldenfeld, p. 146

⇒ in general a cubic term in  $\mathcal{L}$  leads to a first order phase transition, absence of cubic term guarantees a continuous phase transition

However: note that Landau theory is in general not valid for first-order phase transitions!

why?

$\eta \neq 0$  for  $T \rightarrow T_c$ , i.e.  $\eta$  not necessarily small

## Landau theory and coarse graining

- for the physical interpretation of  $\mathcal{L}$  it is instructive to allow for spatially varying order parameters, i.e. for Ising model  $m(\vec{x})$
- allows to connect microscopic theories with classical effective theories, illustrates role of degrees of freedom at different length scales and their systematic treatment

↳ basic idea of RG

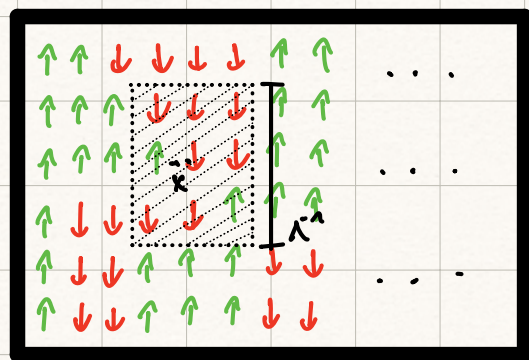
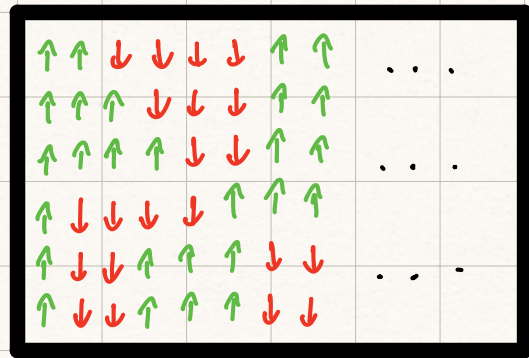
consider spin system with a correlation length  $\xi$

assign a local magnetization  $m(\vec{x})$  to each point in space

via coarse graining:

$$m_\Lambda(\vec{x}) = \frac{1}{N_\Lambda(\vec{x})} \sum_{i \in \vec{x}_\Lambda} \langle \sigma_i \rangle$$

$N_\Lambda(\vec{x}) = \frac{\Lambda^{-d}}{a^d}$  : number of spins in block of size  $\Lambda^{-1}$   
 ↓  
 lattice spacing



$$a \ll \Lambda^{-1} \leq \xi(T)$$

(not the case in the illustration)

⇒  $m_\Lambda(\vec{x})$  is a smooth and slowly varying function, does contain Fourier components of wave numbers  $k \leq \Lambda$

What is the general form of  $\mathcal{L}$  for a system given by  $m_\lambda(\vec{x})$ ?

- a function of the form  $L = \sum_{\vec{x}_i} \mathcal{L}(m_\lambda(\vec{x}_i))$  cannot be complete since minimization with respect to  $m_\lambda(\vec{x})$  would just result in an independent minimization at each point  $\vec{x}_i$ ;

- need to take into account that domain walls, i.e. differences in  $m_\lambda(\vec{x})$  in adjacent blocks cost energy

- Simplest term that takes this into account:

$$\sum_{\vec{x}_i} \sum_{\vec{\delta}} \left( \frac{m_\lambda(\vec{x}_i) - m_\lambda(\vec{x}_i - \vec{\delta})}{\lambda^{-1}} \right)^2 \rightarrow \int d^d \vec{x} \left( \nabla m_\lambda(\vec{x}) \right)^2$$

$$\Rightarrow L = \int d^d \vec{x} \left[ \mathcal{L}(m_\lambda(\vec{x})) + \frac{\sigma}{2} \left( \nabla m_\lambda(\vec{x}) \right)^2 \right]$$

$L$  is a functional of  $m_\lambda(\vec{x})$ , i.e. it depends on entire function at all  $\vec{x}$ , also called effective Hamiltonian, short-distance physics integrated out, effective degree of freedom  $m_\lambda(\vec{x})$  low-energy/long-distance degrees of freedom

How is  $L$  related to the Hamiltonian and the free energy  $F$ ?

$$e^{-\beta F} = \text{Tr} e^{-\beta H}$$

$$\Rightarrow e^{-\beta L(m_\lambda(\vec{x}))} = \text{Tr} e^{-\beta H(\{\sigma_i\})} \delta\left[\sum_{i \in \vec{x}_\lambda} \sigma_i - m_\lambda(\vec{x}) N_\lambda(\vec{x})\right]$$
$$= \text{Tr}' e^{-\beta H(\{\sigma_i\})}$$

↳ partial trace, only configurations with local magnetization  $m_\lambda(\vec{x})$  included

Hence, by introducing  $L[m_\lambda(\vec{x})]$  we have effectively divided the sum over all states ("Tr") into two steps:

$$Z_c = e^{-\beta F}$$
$$= \sum_{\{\sigma_i\}} e^{-\beta H}$$
$$= \sum_{\{\sigma_i^*\}} \underbrace{\sum_{\{\bar{\sigma}_i\}} e^{-\beta H}}_{\text{all microscopic configurations consistent with magnetization } m_\lambda(\vec{x})} = \sum_{\{\sigma_i^*\}} e^{-\beta L[m_\lambda(\vec{x})]}$$

remaining configurations not consistent with  $m_\lambda(\vec{x})$

in the continuum limit the sum amounts to the sum/integral over all coarse-grained functions  $m_\lambda(\vec{x})$  and is written as

$$Z_c = \int \mathcal{D}m_\lambda(\vec{x}) e^{-\beta L[m_\lambda(\vec{x})]}$$

↓  
functional integral

$\mathcal{D}m_\lambda(\vec{x})$  involves an infinite number of integrals in the continuum limit, a discretized version takes the form

$$\int \mathcal{D}m_\lambda(\vec{x}) \rightarrow \prod_{i=1}^N \int dm(\vec{x}_i)$$

in practice the integration over coarse-grained degrees of freedom is often done in momentum space:

$$m_\lambda(\vec{x}) = \frac{1}{(2\pi)^3} \int d^3\vec{k} m_\lambda(\vec{k}) e^{i\vec{k}\cdot\vec{x}}$$

$$m_\lambda(\vec{k}) = \int d^3\vec{x} m_\lambda(\vec{x}) e^{-i\vec{k}\cdot\vec{x}}$$

$$\int \mathcal{D}m_\lambda(\vec{k}) \rightarrow \prod_{|\vec{k}| < \lambda} \int dm_\lambda(\vec{k}_i)$$

the functional  $L[m_\lambda(\vec{x})]$  can in principle be computed starting from the Hamiltonian of a system

↓  
problem set 3: for Ising model